

The DOE Advance CompuTational Software (ACTS) Collection



Discovery 2015: HPC and Cloud
Computing Workshop
Berkeley, California, June 17, 2011

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Computational Research Division
Lawrence Berkeley National Laboratory



OUTLINE

- Motivation
- Introduction to DOE ACTS Collection
- A view of selected functionality in the Collection
- Use of the Tools in the ACTS Collection
- Sustainability through emerging hardware
- Summary

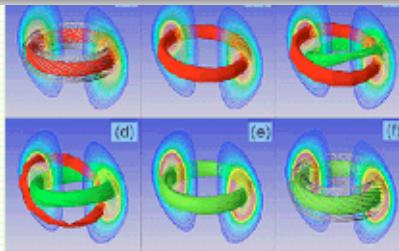
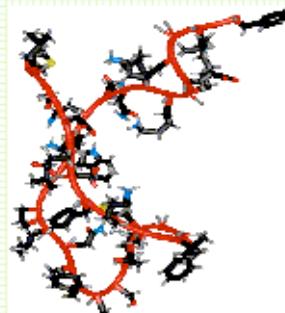
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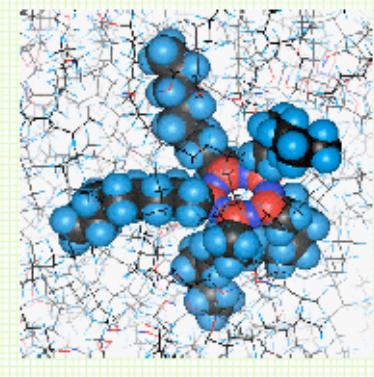
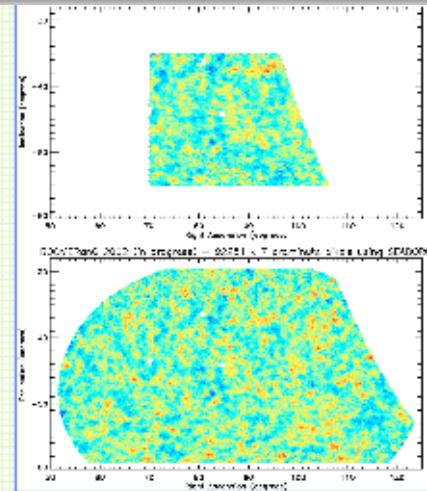


Motivation - HPC Applications

- Accelerator Science
- Astrophysics
- Biology
- Chemistry
- Earth Sciences
- Materials Science
- Nanoscience
- Plasma Science
-
-



GomegaCP is a parallel distributed memory code intended for the modeling and analysis of accelerator cavities, which requires the solution of generalized eigenvalue problems. A parallel direct multi-invert eigenvalue solver in PETSc/PCPACK and SuperLU has allowed for the solution of a problem of order 7.5 million with 204 million unknowns.



Commonalities:

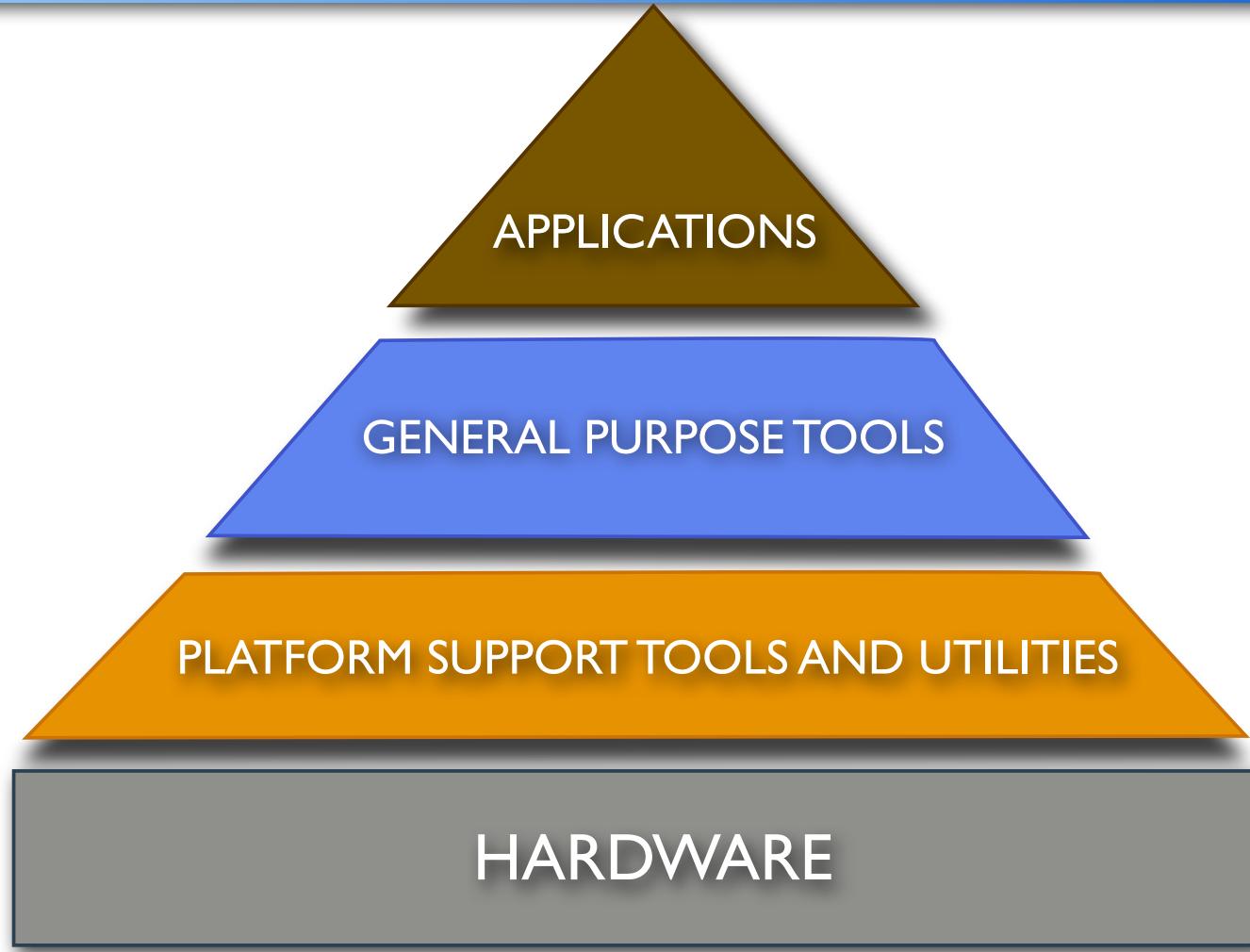
- Major advancements in Science
- Increasing demands for computational power
- Rely on available computational systems, languages, and software tools

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HPC Software Stack

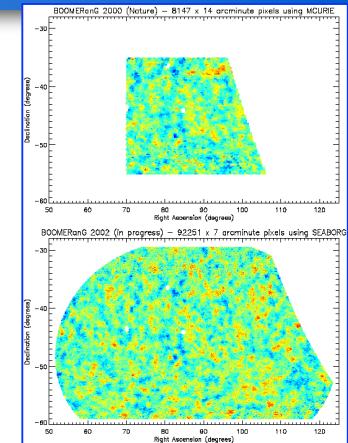
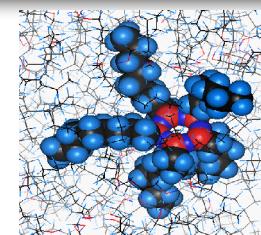
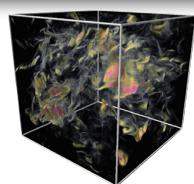
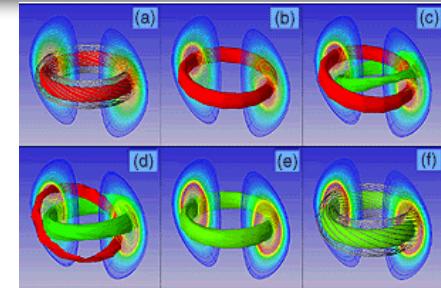


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HPC Software Stack



Omega3P is a parallel distributed-memory code intended for the modeling and analysis of accelerator cavities, which requires the solution of generalized eigenvalue problems. A parallel exact shift-invert eigensolver based on PARPACK and SuperLU has allowed for the solution of a problem of order 7.5 million with 304 million nonzeros.



APPLICATIONS

GENERAL PURPOSE TOOLS

PLATFORM SUPPORT TOOLS AND UTILITIES

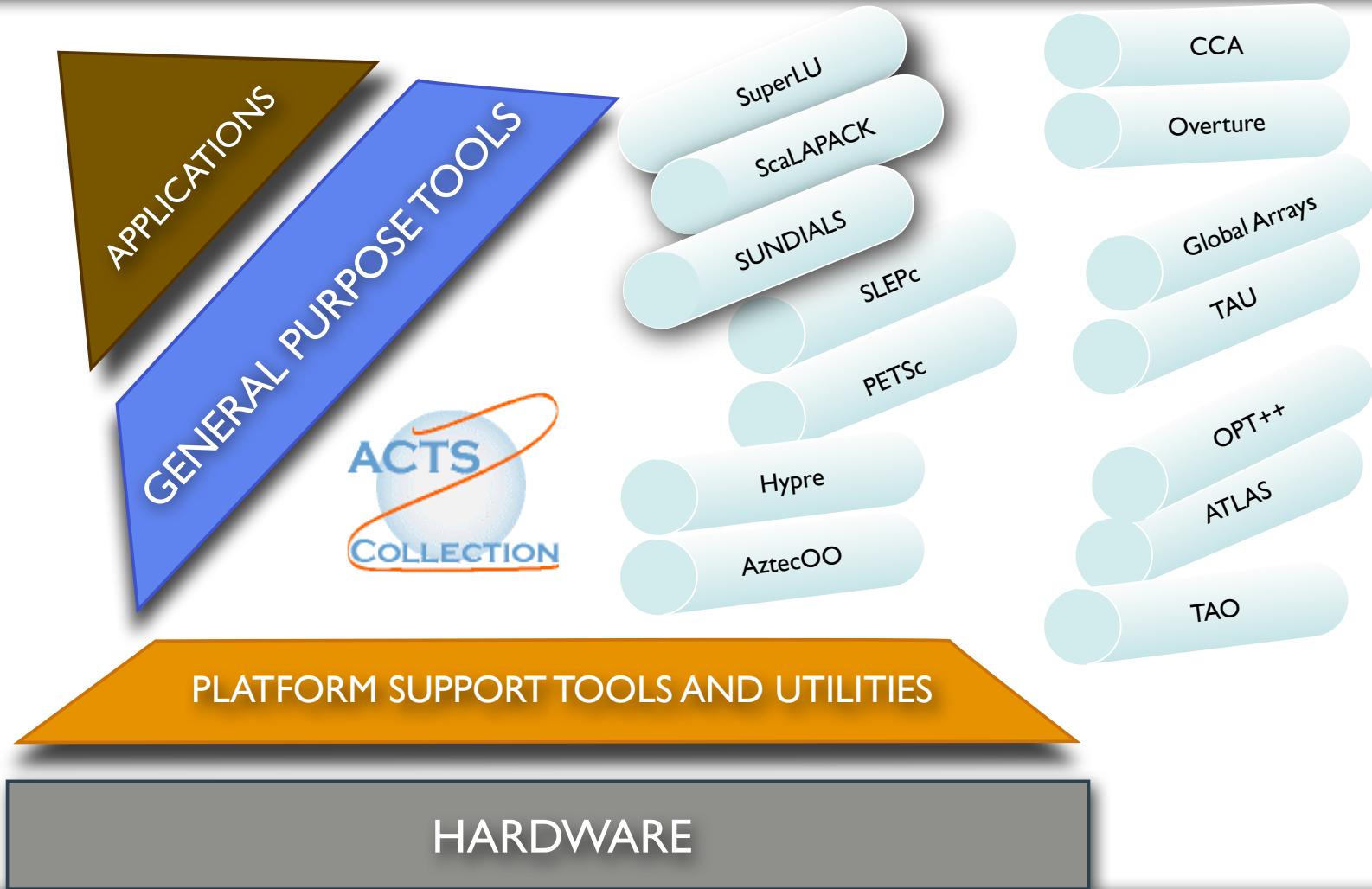
HARDWARE

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HPC Software Stack

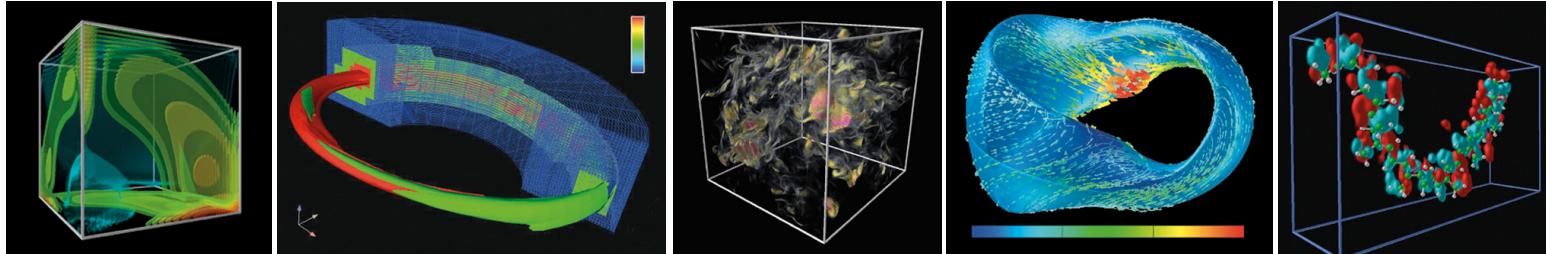


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Goal: The Advanced CompuTational Software Collection (ACTS) makes reliable and efficient software tools more widely used, and more effective in solving the nation's engineering and scientific problems.

References:

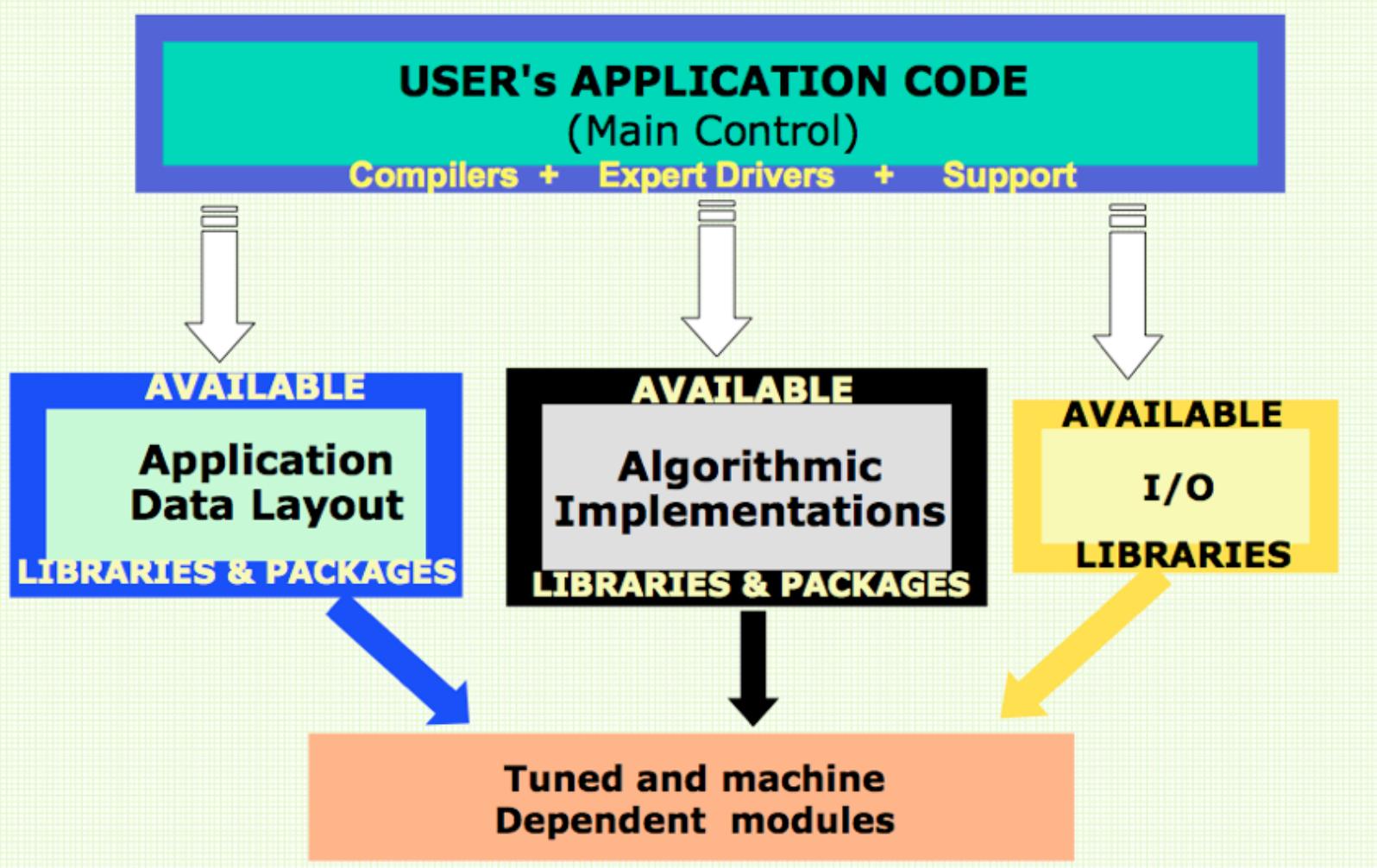
- L.A. Drummond, O. Marques: An Overview of the Advanced CompuTational Software (ACTS) Collection. ACM Transactions on Mathematical Software Vol. 31 pp. 282-301, 2005
- <http://acts.nersc.gov>

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Speeding-Up Software Development



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| Category | Tool | Functionalities |
|---------------------|---------------|--|
| Numerical Libraries | AztecOO | Scalable linear and non-linear solvers using iterative schemes. |
| | Hypre | A family of scalable preconditioners. |
| | PETSc | Scalable linear and non-linear solvers and additional support for PDE related work. |
| | SUNDIALS | Solvers for the solution of systems of ordinary differential equations, nonlinear algebraic equations, and differential-algebraic equations. |
| | ScaLAPACK | High performance parallel dense linear algebra. |
| | SLEPc | Scalable algorithms for the solution of large sparse eigenvalue problems. |
| | SuperLU | Scalable direct solution of large, sparse, nonsymmetric linear systems of equations. |
| | TAO | Large-scale optimization software. |
| Code Development | Global Arrays | Supports the development of parallel programs. |
| | Overture | Supports the development of computational fluid dynamics codes in complex geometries. |
| Run Time Support | TAU | Portable and scalable performance analyzes and tracing tools for C, C++, Fortran and Java programs. |
| Library Development | ATLAS | Automatic generation of optimized numerical dense algebra for scalar processors. |

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Latest Set of Tutorials and Exercises

<http://acts.nersc.gov/events/Workshop2010>

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Upcoming 12th ACTS Collection Workshop

<http://acts.nersc.gov/events/Workshop2011>

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Functionality in The DOE ACTS Collection

| Computational Problem | Methodology | Algorithms | Library |
|-----------------------------|----------------|---|--------------------------------------|
| Systems of Linear Equations | Direct Methods | LU Factorization | ScaLAPACK(dense) SuperLU (sparse) |
| | | Cholesky Factorization | ScaLAPACK |
| | | LDL ^T (Tridiagonal matrices) | ScaLAPACK |
| | | QR Factorization | ScaLAPACK |
| | | QR with column pivoting | ScaLAPACK |
| | | LQ factorization | ScaLAPACK |

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Functionality in The DOE ACTS Collection

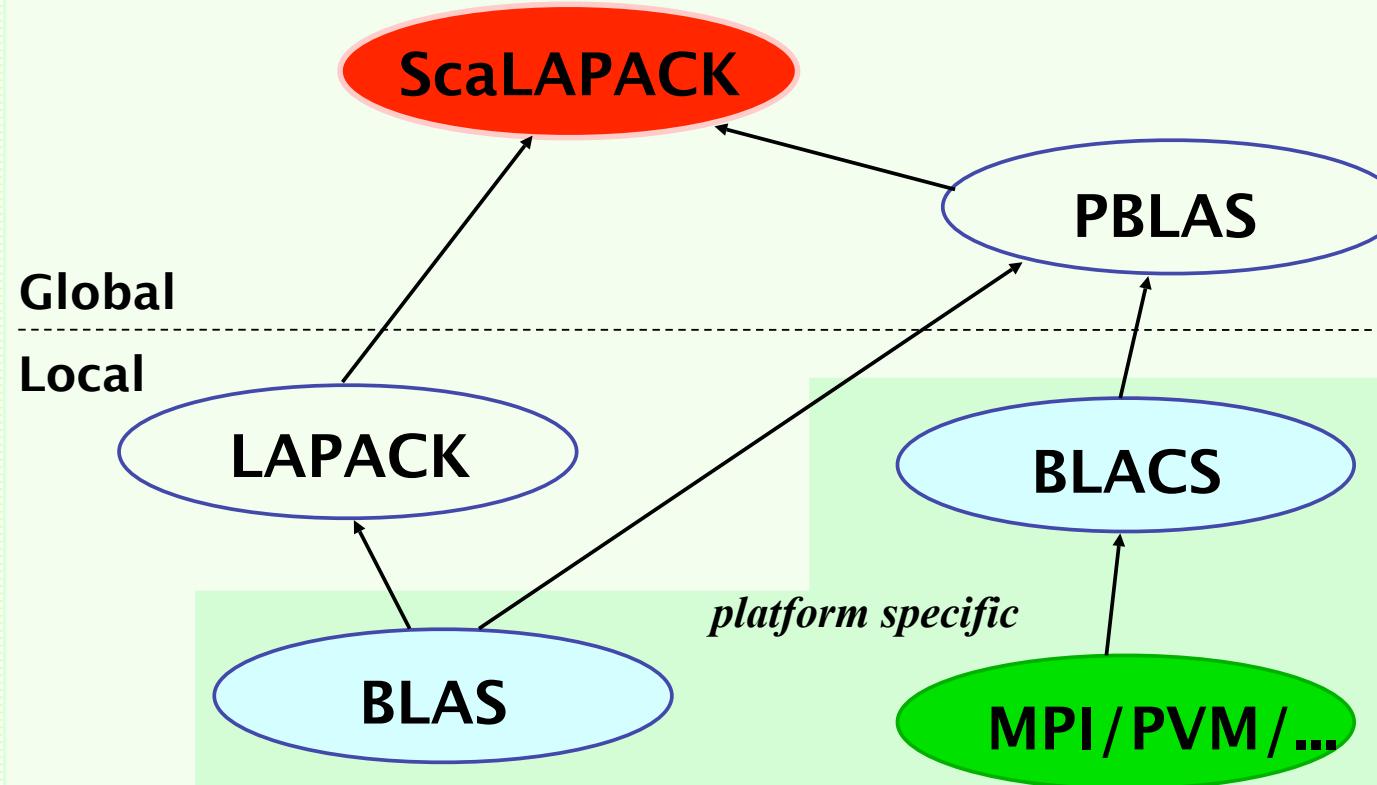
| Computational Problem | Methodology | Algorithms | Library |
|-----------------------------|----------------|---|--------------------------------------|
| Systems of Linear Equations | Direct Methods | LU Factorization | ScaLAPACK(dense) SuperLU (sparse) |
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| | | QR Factorization | ScaLAPACK |
| | | QR with column pivoting | ScaLAPACK |
| | | LQ factorization | ScaLAPACK |

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Software Structure of ScaLAPACK



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Functionality in The DOE ACTS Collection

| Computational Problem | Methodology | Algorithms | Library |
|--|-------------------|------------------------------|-----------------------------|
| Systems of Linear Equations <i>(cont..)</i> | Iterative Methods | Conjugate Gradient | AztecOO (Trilinos) PETSc |
| | | GMRES | AztecOO PETSc Hypre |
| | | CG Squared | AztecOO PETSc |
| | | Bi-CG Stab | AztecOO PETSc |
| | | Quasi-Minimal Residual (QMR) | AztecOO |
| | | Transpose Free QMR | AztecOO PETSc |

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Trilinos



Full Vertical Solver Coverage

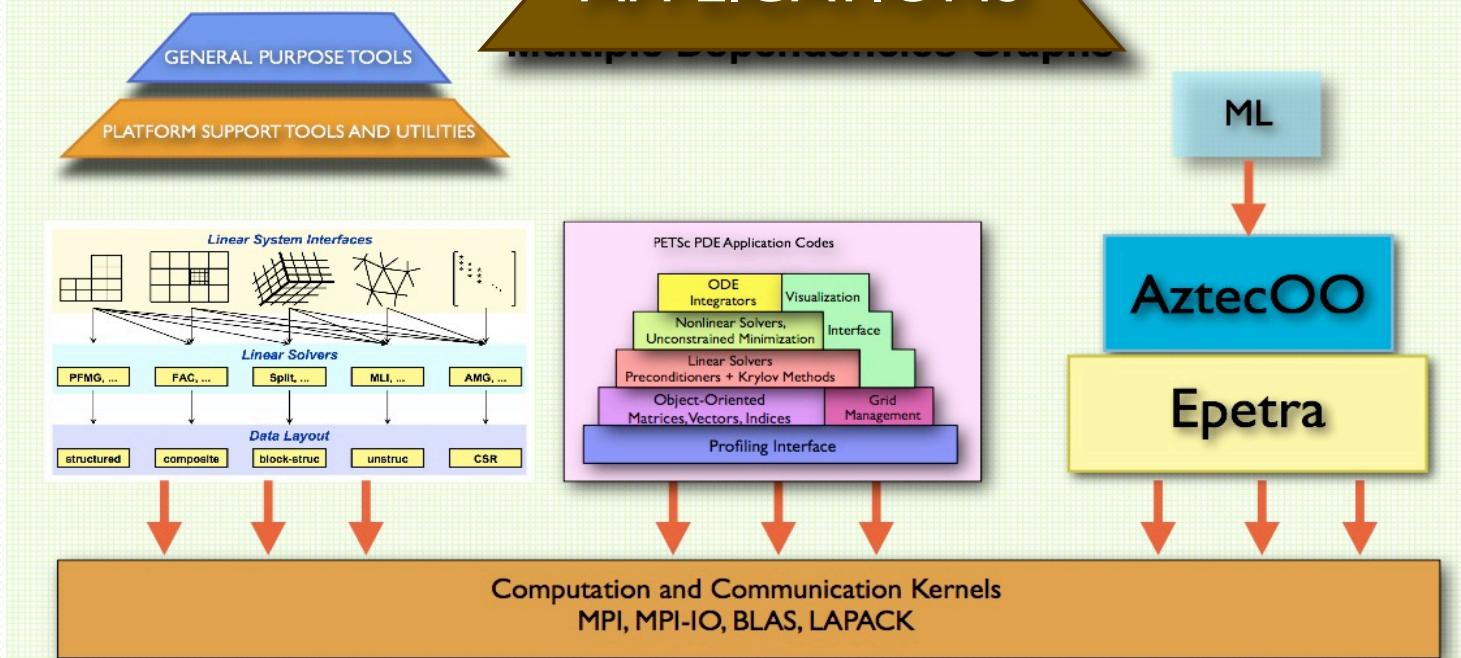


| | | | |
|-----------------------------------|--|--|---|
| Optimization | Find $u \in \Re^n$ that minimizes $g(u)$ | Sensitivities <i>(Automatic Differentiation: Sacado)</i> | MOOCHO |
| Unconstrained: | Find $x \in \Re^m$ and $u \in \Re^n$ that minimizes $g(x, u)$ s.t. $f(x, u) = 0$ | | LOCA |
| Constrained: | | | Rythmos |
| Bifurcation Analysis | Given nonlinear operator $F(x, u) \in \Re^{n+m}$ For $F(x, u) = 0$ find space $u \in U \ni \frac{\partial F}{\partial x}(x, u) = 0$ | | NOX |
| Transient Problems | Solve $f(\dot{x}(t), x(t), t) = 0$ $t \in [0, T], x(0) = x_0, \dot{x}(0) = x'_0$ for $x(t) \in \Re^n, t \in [0, T]$ | | AztecOO Belos Ifpack, ML, etc... Anasazi |
| Nonlinear Problems | Given nonlinear operator $F(x) \in \Re^m \rightarrow \Re^m$ Solve $F(x) = 0 \quad x \in \Re^m$ | | Epetra Tpetra |
| Linear Problems | Given Linear Ops (Matrices) $A, B \in \Re^{m \times n}$ | | |
| Linear Equations: | Solve $Ax = b$ for $x \in \Re^n$ | | |
| Eigen Problems: | Solve $A\nu = \lambda B\nu$ for (all) $\nu \in \Re^n, \lambda \in \Re$ | | |
| Distributed Linear Algebra | | | |
| Matrix/Graph Equations: | Compute $y = Ax; A = A(G); A \in \Re^{m \times n}, G \in \mathbb{S}^{m \times n}$ | | |
| Vector Problems: | Compute $y = \alpha x + \beta w; \alpha = \langle x, y \rangle; x, y \in \Re^n$ | | |

Overlapping Functionality

Iterative Schemes for
Linear and Non-Linear Solvers

APPLICATIONS



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Functionality in The DOE ACTS Collection

| Computational Problem | Methodology | Algorithms | Library |
|--|-------------------|------------------------------|-----------------------------|
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| | | GMRES | AztecOO PETSc Hypre |
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| Computational Problem | Methodology | Algorithms | Library |
|---|-------------------------------|--------------------------------|---------------------------|
| Systems of Linear Equations (cont..) | Iterative Methods (cont..) | SYMMQLQ | PETSc |
| | | Precondition CG | AztecOO PETSc Hypre |
| | | Richardson | PETSc |
| | | Block Jacobi Preconditioner | AztecOO PETSc Hypre |
| | | Point Jocobi Preconditioner | AztecOO |
| | | Least Squares Polynomials | PETSc |

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Functionality in The DOE ACTS Collection

| Computational Problem | Methodology | Algorithms | Library |
|--|--------------------------------------|------------------------------------|---------------------------|
| Systems of Linear Equations <i>(cont..)</i> | Iterative Methods <i>(cont..)</i> | SOR Preconditioning | PETSc |
| | | Overlapping Additive Schwartz | PETSc |
| | | Approximate Inverse | Hypre |
| | | Sparse LU preconditioner | AztecOO PETSc Hypre |
| | | Incomplete LU (ILU) preconditioner | AztecOO |
| | MultiGrid (MG) Methods | Least Squares Polynomials | PETSc |
| | | MG Preconditioner | PETSc Hypre |
| | | Algebraic MG | Hypre |
| | | Semi-coarsening | Hypre |

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Functionality in The DOE ACTS Collection

| Computational Problem | Methodology | Algorithm | Library |
|---|------------------------------|---|-------------------------------------|
| Linear Least Squares Problems | Least Squares | $\min_x \ b - Ax \ _2$ | ScaLAPACK |
| | Minimum Norm Solution | $\min_x \ x \ _2$ | ScaLAPACK |
| | Minimum Norm Least Squares | $\min_x \ b - Ax \ _2$ $\min_x \ x \ _2$ | ScaLAPACK |
| Standard Eigenvalue Problem | Symmetric Eigenvalue Problem | $Az = \lambda z$ For $A=A^H$ or $A=A^T$ | ScaLAPACK (dense) SLEPc (sparse) |
| Singular Value Problem | Singular Value Decomposition | $A = U\Sigma V^T$ $A = U\Sigma V^H$ | ScaLAPACK (dense) SLEPc (sparse) |
| Generalized Symmetric Definite Eigenproblem | Eigenproblem | $Az = \lambda Bz$ $ABz = \lambda z$ $BAz = \lambda z$ | ScaLAPACK (dense) SLEPc (sparse) |

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Functionality in The DOE ACTS Collection

| Computational Problem | Methodology | Algorithm | Library |
|-----------------------|--------------|-------------------------------|---------|
| Non-Linear Equations | Newton Based | Line Search | PETSc |
| | | Trust Regions | PETSc |
| | | Pseudo-Transient Continuation | PETSc |
| | | Matrix Free | PETSc |

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Functionality in The DOE ACTS Collection

| Computational Problem | Methodology | Algorithm | Library |
|-------------------------|---------------|---------------------------|--------------|
| Non-Linear Optimization | Newton Based | Newton | OPT++ TAO |
| | | Finite-Difference Newton | OPT++ TAO |
| | | Quasi-Newton | OPT++ TAO |
| | | Non-linear Interior Point | OPT++ TAO |
| | CG | Standard Non-linear CG | OPT++ TAO |
| | | Limited Memory BFGS | OPT++ |
| | | Gradient Projections | TAO |
| | Direct Search | No derivate information | OPT++ |

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| Computational Problem | Methodology | Algorithm | Library |
|----------------------------------|-------------------------------|--|----------------------------|
| Non-Linear Optimization (cont..) | Semismoothing | Feasible Semismooth | TAO |
| | | Unfeasible semismooth | TAO |
| Ordinary Differential Equations | Integration | Adam-Moulton (Variable coefficient forms) | CVODE (SUNDIALS) CVODES |
| | | Backward Differential Formula | CVODE CVODES |
| Nonlinear Algebraic Equations | Inexact Newton | Line Search | KINSOL (SUNDIALS) |
| Differential Algebraic Equations | Backward Differential Formula | Direct and Iterative Solvers | IDA (SUNDIALS) |

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Functionality in The DOE ACTS Collection

| Computational Problem | Support | Techniques | Library |
|---------------------------|--------------------|-------------------|----------------------------|
| Writing Parallel Programs | Distributed Arrays | Shared-Memory | Global Arrays |
| | | Grid Generation | OVERTURE |
| | | Structured Meshes | Hypre OVERTURE PETSc |
| | | | Hypre OVERTURE |

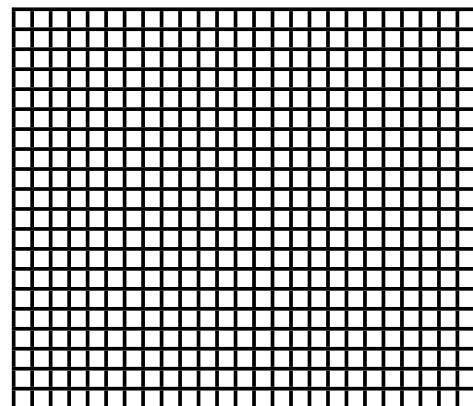
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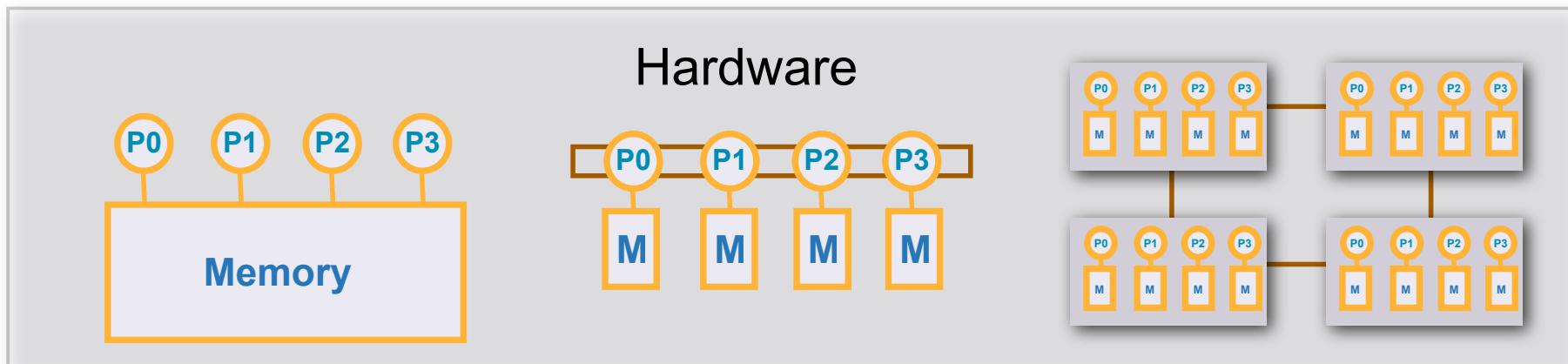
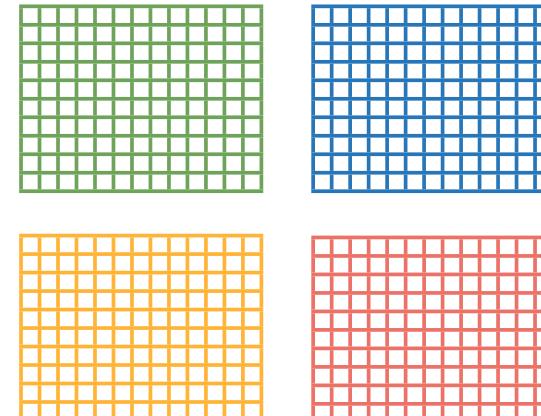


Parallel Programming Paradigm

A



Parallelization

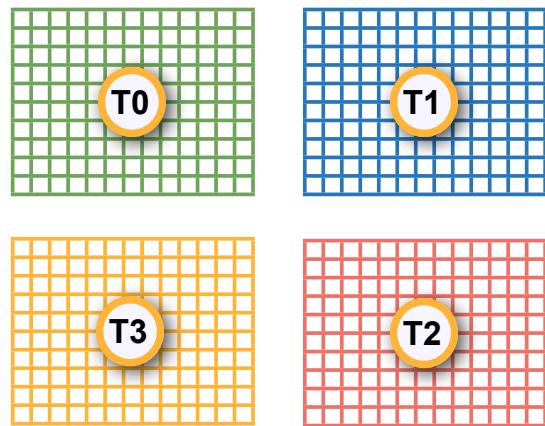


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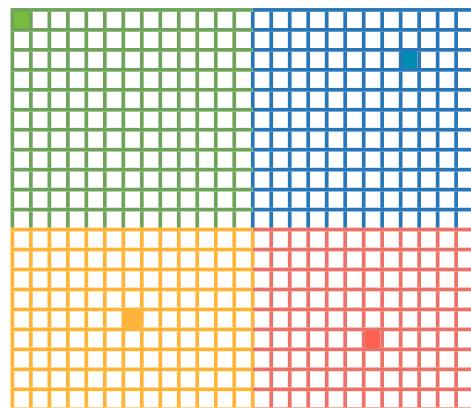
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Shared Memory Programming Paradigm



Program Design Considerations

- Data Distribution (problem partition)
- Interprocess work coordination
 - load sharing
 - communication
 - synchronization



T0 T1 T2 T3

Global View and Access to the data

A(1,1) A(3,22)

A(16,7) A(17,20)

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Comparing Programming Paradigms



Message Passing Paradigm (MPI or PVM)

```
if (my_id != 0) {
    1) pack data in message
    2) send message to task 0
else for i=1,3 {
    receive message from task ( i )
    unpack message
    place the data in message received in local data array }
end if
```

Global Arrays

```
if (my_id != 0) {
    NGA_GET(A,lo,hi,local_array,stride)
else for i=1,3 {
    NGA_PUT(A,lo,hi,local_array,stride)
end if
```

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Functionality in The DOE ACTS Collection

| Computational Problem | Support | Technique | Library |
|-----------------------|-------------------------|---------------------------|---------|
| Profiling | Algorithmic Performance | Automatic instrumentation | PETSc |
| | | User Instrumentation | PETSc |
| | Execution Performance | Automatic Instrumentation | TAU |
| | | User Instrumentation | TAU |
| Code Optimization | Library Installation | Linear Algebra Tuning | ATLAS |

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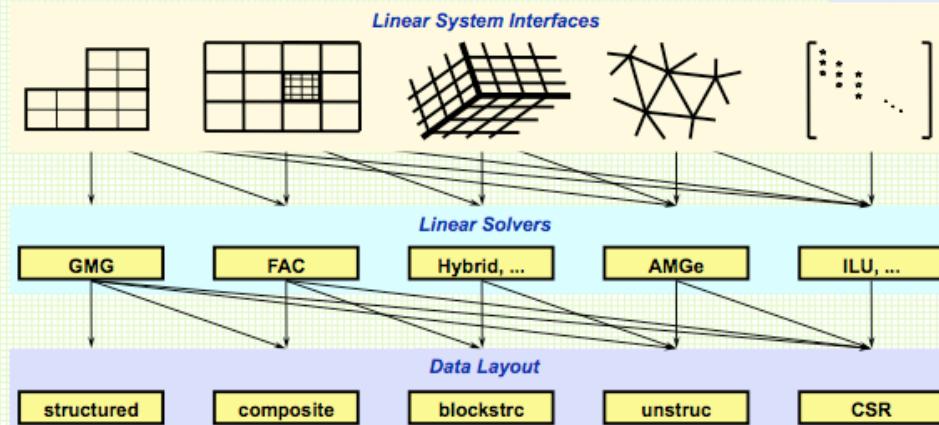
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User Interfaces

```
CALL BLACS_GET( -1, 0, ICTXT )
CALL BLACS_GRIDINIT( ICTXT, 'Row-major', NPROW, NPCOL )
:
CALL BLACS_GRIDINFO( ICTXT, NPROW, NPCOL, MYROW, MYCOL )
:
:
CALL PDGESV( N, NRHS, A, IA, JA, DESCA, IPIV, B, IB, JB, DESC B,
$           INFO )
```

Command lines



Library Calls

- `-ksp_type [cg,gmres,bcgs,tfqmr, ...]`
- `-pc_type [lu,ilu,jacobi,sor,asm, ...]`

More advanced:

- `-ksp_max_it <max_iters>`
- `-ksp_gmres_restart <restart>`
- `-pc_asm_overlap <overlap>`

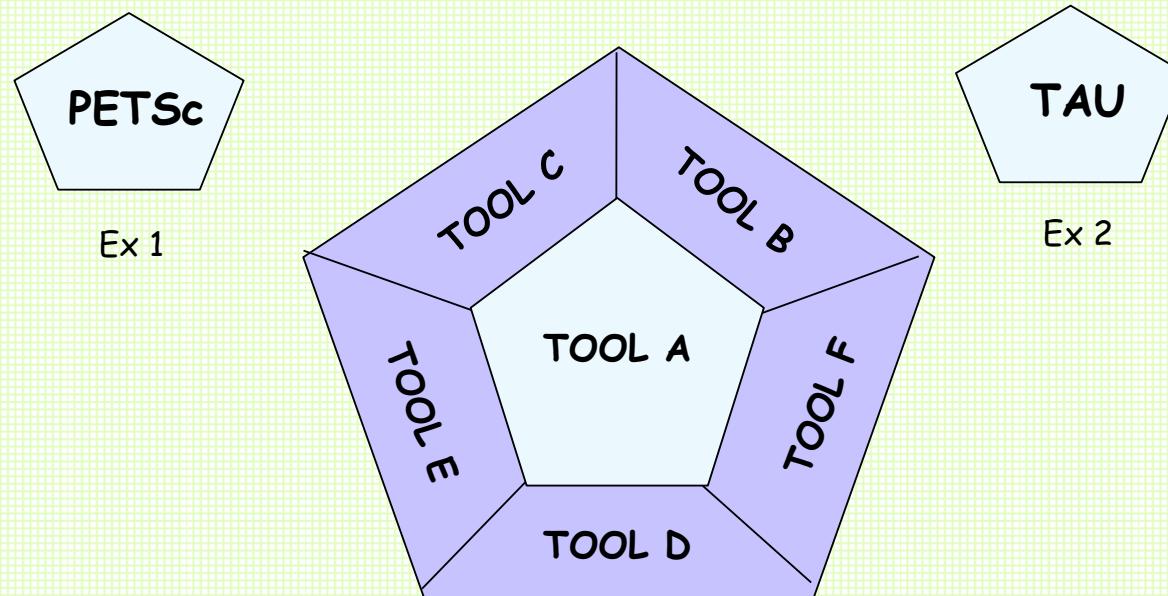
Problem Domain

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Interoperability

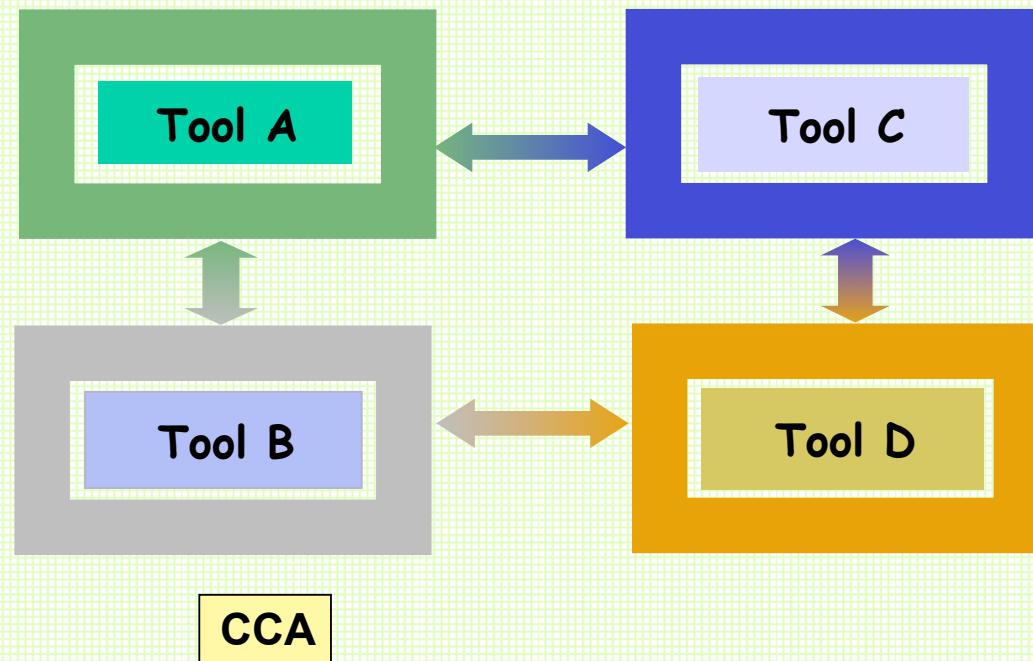


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Interoperability

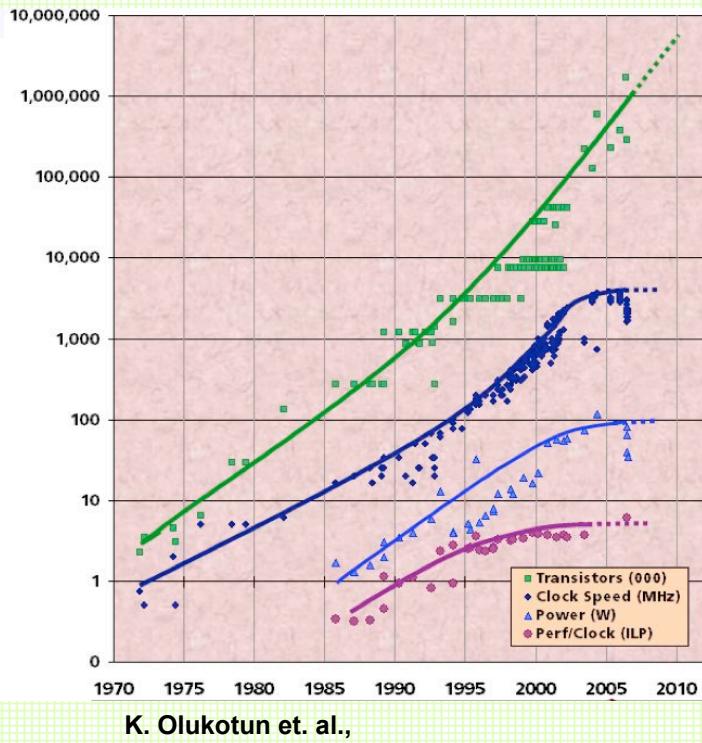


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Scalability and Sustainability



- Number of cores per node will continue to increase.
- Memory per node is not increasing at the same rate

Looking back in history. . .

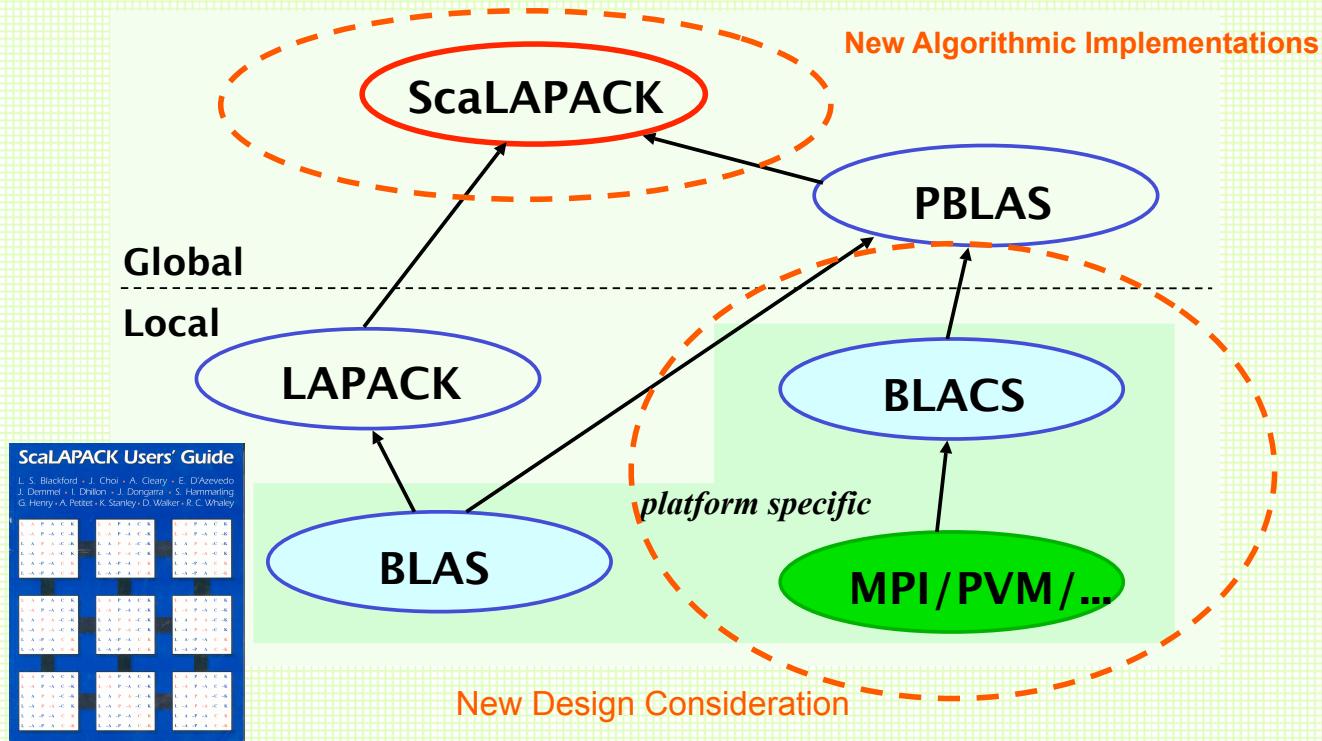
- Processor speed increased at faster rate than memory speed.
- Memory bandwidth relevant to overall performance

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Scalability and Sustainability

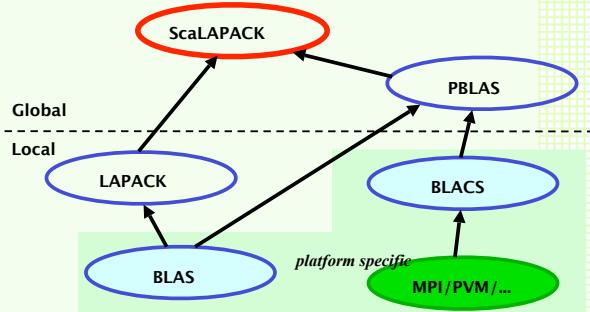


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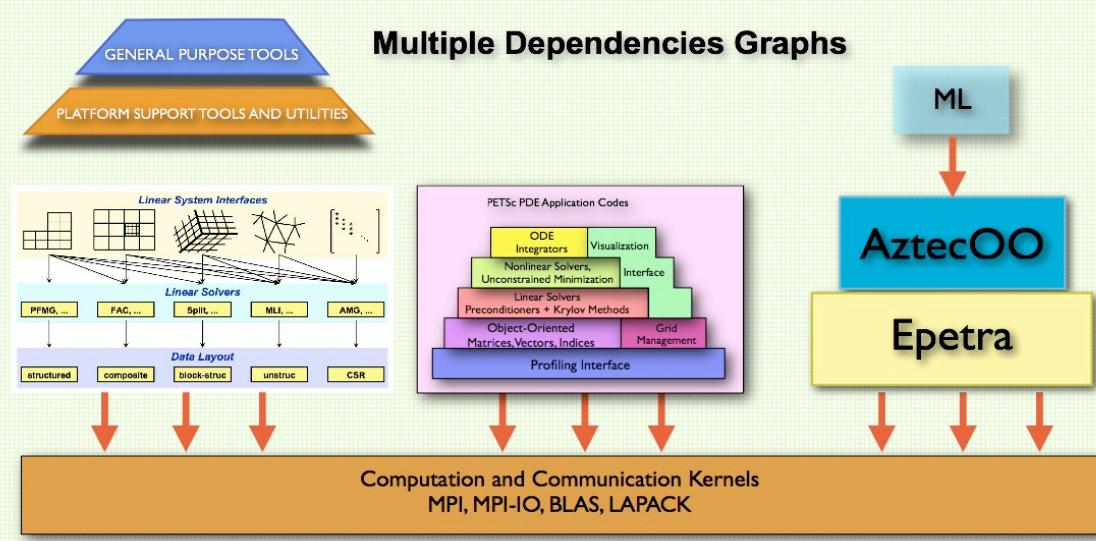
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Software Dependency Graph



- Identify key common kernels
- Identify parameters that drive performance
- Profile and test (bottom-up)

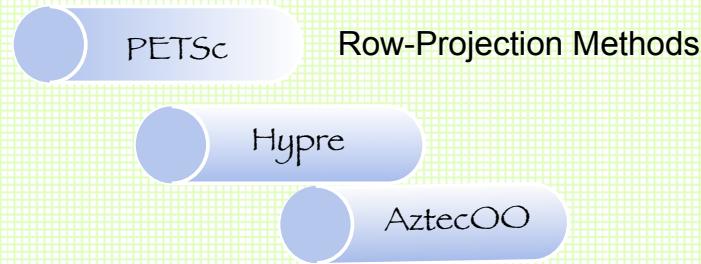
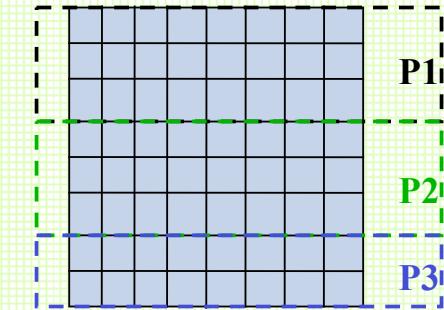


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Kernel Optimization



5x5 matrix partitioned in 2x2 blocks

$$\begin{pmatrix} a_{11} & a_{12} & | & a_{13} & a_{14} & | & a_{15} \\ a_{21} & a_{22} & | & a_{23} & a_{24} & | & a_{25} \\ \hline a_{31} & a_{32} & | & a_{33} & a_{34} & | & a_{35} \\ a_{41} & a_{42} & | & a_{43} & a_{44} & | & a_{45} \\ \hline a_{51} & a_{52} & | & a_{53} & a_{54} & | & a_{55} \end{pmatrix}$$

2x2 process grid point of view

$$\begin{array}{cc|cc} a_{11} & a_{12} & a_{13} & a_{14} \\ a_{21} & a_0 & a_{23} & a_{24} \\ \hline a_{51} & a_{52} & a_{53} & a_{54} \\ \hline a_{31} & a_{32} & a_{33} & a_{34} \\ a_{41} & a_2 & a_{43} & a_{44} \\ \hline a_{41} & a_{42} & a_{43} & a_{44} \end{array} \rightarrow \begin{array}{cc|cc} a_{11} & a_{12} & a_{13} & a_{14} \\ a_{21} & a_0 & a_{23} & a_{24} \\ \hline a_{51} & a_{52} & a_{53} & a_{54} \\ \hline a_{31} & a_{32} & a_{33} & a_{34} \\ a_{41} & a_2 & a_{43} & a_{44} \\ \hline a_{41} & a_{42} & a_{43} & a_{44} \end{array}$$

PETSc Row-Projection Methods

Hypre

AztecOO

Dense Linear Algebra

SuperLU

ScaLAPACK

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Kernel Optimization

$Ax = b$ or $AX = B$
 $Hx = b'$
 $\min_x \| b - Ax \|_2$
 $\min_x \| x \|_2$
 $\min_x \| b - Ax \|_2$
 $\min_x \| x \|_2$
 $Az = \lambda z$
 $A = U\Sigma V^T$
 $A = U\Sigma V^H$
 $Az = \lambda Bz$
 $ABz = \lambda z$
 $BAz = \lambda z$

Exploit concurrency :

(in and out a node)

- Hybrid programming (MPI+threads)
- NUMA Aware operations

Kernel reusability:

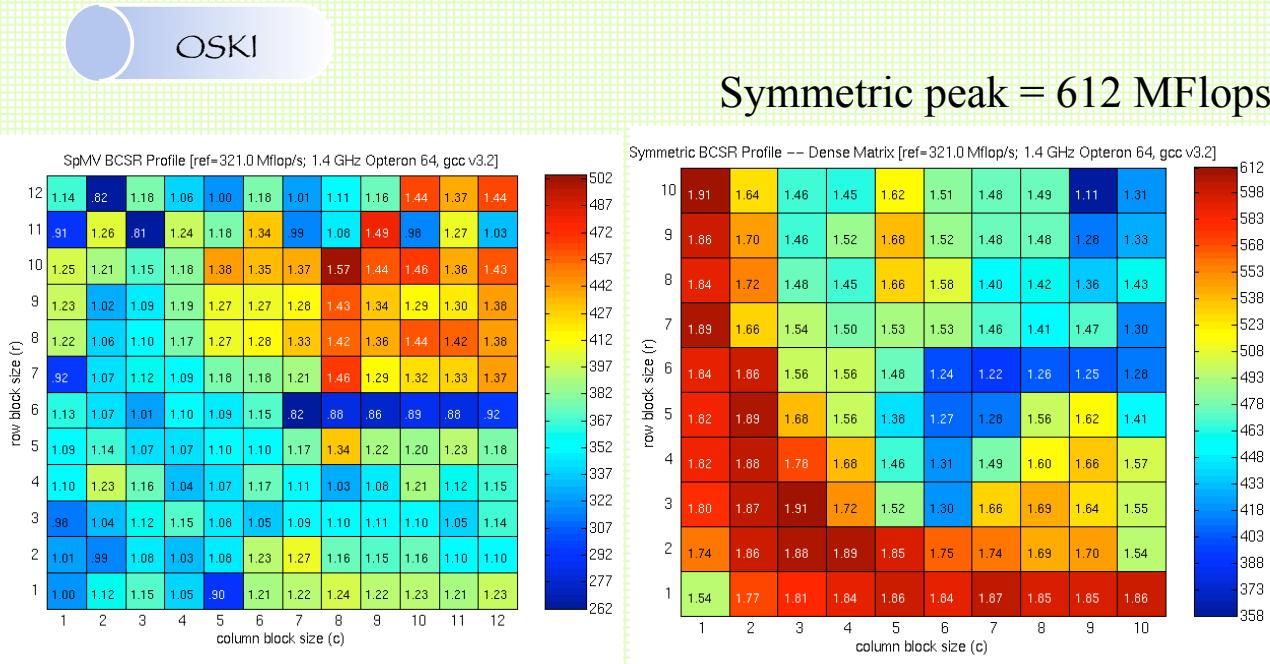
- Bottom-Up automatic optimization
- Identify key parameters in the algorithm
- Run-time parameter control

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Functionality in The DOE ACTS Collection



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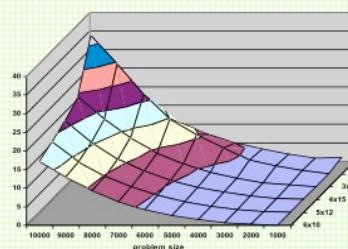


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ACTS Software Sustainability Cycle

Profiling and Tracing Tools: TAU

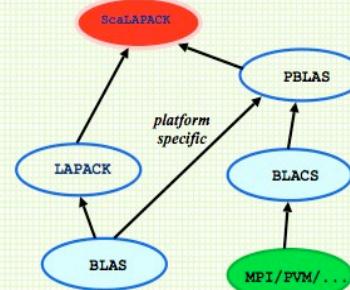
Execution time of PDPDSV for various grid shapes



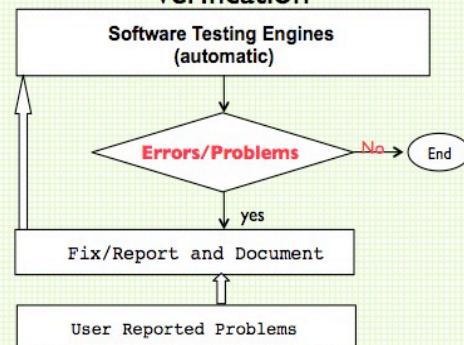
Performance and Scalability



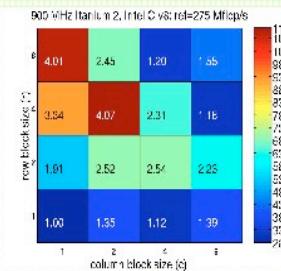
Software Dependency Graph



Automatic Testing and Verification



Auto-Tuning (OSKI, ATLAS,)



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Summary

min[time_to_first_solution] (prototype)

→ **min[time_to_solution]** (production)

- Outlive Complexity
 - Increasingly sophisticated models
 - Model coupling
 - Interdisciplinary
- Sustained Performance
 - Increasingly complex algorithms
 - Increasingly diverse architectures
 - Increasingly demanding applications

} (Software Evolution)

} (Long-term deliverables)

→ **min[software-development-cost]**

max[software_life] and **max[resource_utilization]**

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